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Analogy in Verification of State-Based Specifications. First Results

> Erica Melis<sup>1</sup>, Claus Sengler<sup>2</sup> SEKI Report SR-96-13

# Analogy in Verification of State-Based Specifications. First Results

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#### Abstract

Saving user interaction reduces the costs of program verification. This paper describes an internal analogy technique that reuses subproofs in the verification of state-based specifications. It identifies common patterns of subproofs and their justifications in order to employ them in the reuse of subproofs.

## 1 Introduction

Typically, in formal software verification many and very large proof obligations have to be satisfied rather than complicated to prove obligations. This requires a considerable number of relatively simple subproofs to be accomplished by the user supported by the verification system. Even if the percentage of interactive steps may sound small, it amounts to quite an effort for proofs with ten thousands of proof steps. Consequently, a major problem in software verification is the tremendous amount of user interaction needed. To minimize the user interaction is therefore a primary goal in order to reduce the costs of verified software that are some five to ten times the costs of ordinary software. The reuse of user-guided subproofs can contribute to that goal.

A class of real world software verification problems have state-based specifications. State-based means that an invariant, e.g. a reliability statement, has to be proved for an initial state  $p_0$  and for all states that can be reached by certain (admissible) state transitions  $T_i$ . Put formally, the theorem to be proved is

$$Inv(p_0) \bigwedge_{i} (Inv(p) \to Inv(T_i(p))), \tag{1}$$

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where usually, the invariant Inv(X) is a conjunction with many conjuncts and the proof of  $Inv(p) \rightarrow Inv(T_i(p))$  can be similar for different state transitions  $T_i$ . Therefore, a decomposition of the theorem gives many similar proof obligations. This situation gives many similar proof obligations in one verification task and naturally suggests a reuse of subproofs.

Reusing proofs has been addressed in different settings. A reuse of proofs in program verification after slightly changing programs is addressed in [9]. External analogy, i.e., analogy between proofs of *different* theorems has been described in [6] and reuse of generalized rewrite proofs is described in [4]. As far as we know, internal analogy for verifying state-based specifications has not been tackled before.

This paper is organized as follows. First we describe the internal analogy paradigm suitable for reusing subproofs within the same large proof attempt. In particular, the reuse in verifying state-based specifications is addressed. Then we illustrate the usage of internal analogy with an example that is taken from a case study that, among others, verified a state-based specification.

#### Notation

We work with a sequent calculus; for other calculi the procedure can be adapted.  $H_1, \ldots, H_n \vdash C_1, \ldots, C_m$  abbreviates the sequent  $H_1 \land \ldots \land H_n \vdash C_1 \lor \ldots \lor C_m$ . A normal form (NF) of this sequent is the set  $\{H_1, \ldots, H_n, \neg C_1, \ldots, \neg C_m\}$ . Note that this normal form does not distinguish between variants having, e.g., H as hypothesis and having  $\neg H$  in the conclusion, respectively. A proof obligation is provable if for a formula H, H and  $\neg H$  belong to its NF. Variables are  $\forall$ quantified if not stated otherwise.

## 2 Internal Derivational Analogy in the Verification of State-Based Specifications

Analogy in problem solving transfers the solution or the problem solving experience of a *source* problem to guide the problem solving for a similar *target* problem. In general, the process of reasoning by analogy can be described as follows. A case base is kept of previously solved problems with accompanying solutions. When a new target problem is encountered, a similar problem is retrieved from this case base and its solution is used as a guide to the solution of the new problem by analogical replay.

Analogy requires to map, and sometimes to reformulate, the source problem to the target problem, to extend the mapping and reformulation to the solutions, to replay, as well as to adapt the solution to the requirements of the target.

Derivational analogy [1] guides the target solution by replaying decisions of the source problem solving *process*, and it uses information about reasons for the decisions (*justifications*).

Internal analogy [2, 7] is a process that transfers experience from a completed subgoal (source) in the same problem solving process to solve a current subgoal

(target). That is, in internal analogy the source and the target are subproblems of a single problem. Therefore, this technique does not require the effort to set up a permanent case base and needs relatively little search for the retrieval of a source, as opposed to analogy in general. Furthermore, little or no effort at all is required for mapping because corresponding subgoals in one proof are very similar.

Still, internal analogy needs some storing of justifications and mapping effort and hence, internal analogy pays in particular when it replaces search-intensive subtasks or interaction-intensive subtasks, see [7].

#### 2.1 Internal Analogy for State-Based Verification

Using internal analogy in software verification replaces interaction-intensive subtasks. The accumulation of a library of cases is not required in our internal analogy. Usually, the subproofs need only to be cached, and often the source terms need not to be mapped into different target terms.

The internal analogy has two steps, retrieval and replay. Two modes of the retrieval are possible for the internal analogy described in this paper:

- The retrieval of a source is done automatically.
- The source is provided interactively.

In the first case, the analogy procedure includes searching for a source which is left to the user in the second case. The automated retrieval searches for (source) nodes in the proof plan the proof obligations of which are proved already and that have justifications holding in the current (target) node. For instance, as described in sections 2.2 and 3, the search for a reusable subproof automatically compares the essence justification of source nodes with the NF of the target problem. An efficient retrieval can be achieved by (lexicographically) ordering the formulae in the justifications and in the NFs. Henceforth, we use "NF" for ordered NF.

The analogical replay is an automated one in any case. It is given in a nutshell in Table 1. The justifications are checked in order to perform a warranted analogical transfer only. Its check of justifications is also simplified by ordering the formulae in the NF. The replayed subplan  $\pi$  may consist of a single step  $c_i$ , of several steps, or even of the whole source subplan. The "next usable step" depends on the satisfied justification j of  $c_i$  in C. All the steps that belong to the subplet of conseptontial derivational property general steps of justifications afightheory is proofinite proving the subplance is given by the subplet of the subplet

#### 2.2 Justifications

Justifications represent reasons for proof decisions. It is a non-trivial task to select appropriate justifications in a proof planning environment. For inductive theorem proving this task and a set of appropriate justifications is described in [5] and [7].

Our justifications are represented in a data structure attached to the proof plan nodes. This justification structure has different slots that store different input: source goal, guiding source subplan, target goal output: (partial) target plan

- 1. Let C be the guiding subplan and  $c_i$  the current step in C.
- 2. Terminate if the target goal is proved.
- 3. Check of justifications: If the justification of  $c_i$  that corresponds to a subplan  $\pi$  holds in the target, then replay  $\pi$ .
- 4. Advance the case C to the next usable step  $c_j$ ;  $i \leftarrow j$ ; goto 2.

Table 1: Outline of the analogical replay

kinds of justifications, as explained below. The justifications are checked during the replay. Only if at least one kind of justification holds, the corresponding step or the subplan can be replayed.

For the verification of state-based specifications we analyzed the most common proof patterns and associated them with appropriate justifications. Frequent proof patterns are: (i) the reduction to small essential proof obligations by extracting *relevant* subformulae, (ii) the use of derived lemmata, and (iii) term generalization. These patterns can be combined in a proof.

In order to make the effort for analogy that includes checking the justifications as small as possible, we need to

- store all the information *relevant* for the replay but not more,
- store it in a form that is *available* during the source solution process and that can be *easily interpreted* in the target.

Taking into consideration the two requirements, we identified the following justifications for state-based specifications.

1. The user reduces the problem to essential proof obligations: If a proof obligation at a root node  $N_0$ 

$$H_1,\ldots,H_n\vdash C_1,\ldots,C_m$$

is reduced to a proof of a sequent

$$H_{i_1},\ldots,H_{i_l}\vdash C_{j_1},\ldots,C_{j_k}$$

for  $i_1, i_l \in \{1, \ldots, n\}$  and  $j_1, j_k \in \{1, \ldots, m\}$ , then the NF of the reduced sequent, called *essence*, is stored as a justification in the essence slot, e.g., (essence:  $\{H_{i_1}, \ldots, H_{i_l}, \neg C_{j_1}, \ldots, \neg C_{j_k}\}$ ). essence contains all the relevant subformulae. Note that essence is a justification for a whole subproof rather than for single proof steps. Therefore, this justification is stored after the subproof has been completed. It is computed by goal regression [8] over the whole subproof.

For a new subproblem in a node N it can be checked automatically whether its NF is a superset of  $N_0$ 's essence. That is, it is checked whether the source and the target problem differ in irrelevant subformulae only. If yes, the subproof at  $N_0$  can be fully replayed. In a target node, the essence is the justification checked first.

- **Example:** The essence of 5.3. below is a subset of the NF of 5.8. The rest of the proof obligation does not matter, and so the subproof of 5.3. can completely be replayed.
- Interpretation: If the NF of a target proof obligation is a superset of the NF in the justification slot essence, then this justification holds, and the source subproof can be replayed.

Even in cases where no reduction was performed in the source, it is reasonable to store the essence of a subproof in order to be able to discover a similar essence of a target problem later on.

- 2. The user provides a lemma in the source that enables or considerably simplifies the proof. For instance in several subproofs of the example below, the lemma  $x \in insert(Y, Z) \land x \notin Z \Rightarrow x \equiv Y$  is provided<sup>1</sup> that helps to complete several subproofs. The subset of (generalized) elements of the source NF that is needed to apply the lemma is stored as a justification in the lemma justification. lemma is computed by goal regression (backward) from the lemma application node  $N_l$ . The current value of the regressed goal is stored as lemma justification at each node visited by the goal regression.
  - **Example:** In example 5.3. below, the lemma justification at node  $N_0$  is:  $\{x \in err, err \equiv insert(next(in'), err'), \neg(x \in err')\}$  because the goal regression yields  $\{x \in insert(next(in'), err'), \neg(x \in err')\}$  in the first step and  $\{x \in err, err \equiv insert(next(in'), err'), \neg(x \in err')\}$  in the second step.
  - Interpretation: If the NF of the target problem is a superset of the source node's lemma justification, then the justification holds, and the lemma can be applied in the target.

lemma is a justification for several steps rather than for a large subproof.

- 3. An extended form of the justification check does not require the source essence to be an exact subset of the target NF but additionally allows for a substitution of variables or even a mapping of terms. This more general g-lemma justification is produced by
  - 1. in lemma replacing the substitution terms by the variables of the lemma they are substituted for and
  - 2. replacing other constants not occurring in the lemma by variables.

<sup>&</sup>lt;sup>1</sup>The semantics of the functions does not play a role at this moment. It will be explained in section 3.

When we replace the lemma subset by the g-lemma subset in essence, we also obtain a more general g-essence.

- **Example:** From the lemma justification above and from the substitution  $[Y \leftarrow next(in'), Z \leftarrow err']$ , the g-lemma justification  $\{x \in B, B \equiv insert(Y, Z), \neg (x \in Z)\}$  is produced.
- Interpretation: If g-lemma of a source node *matches* a subset of the NF of the target problem, then the justification holds and the lemma can be applied in the target node again. If the g-essence of a source matches a subset of the NF of the target problem, then the justification holds and the source subproof can be replayed.
- 4. Often, the theorem provers of a verification system are not able to prove a proof obligation without a user supplied generalization. Automated generalization is a very difficult task and, therefore, most often left to the user.

The justifications gen-essence and gen-lemma, stored at a generalization node  $N_G$  of a plan, is produced by computing the essence and lemma of the generalized goal, respectively.

- **Example:** The proof of 6.3. in section 3 includes the term generalization  $max\_value(sender(next(in')), clients')$  to X and of value(next(in')) to Y at node  $N_G$ . The gen-essence for the node is  $\{(X < Y), \neg(Y > X)\}$ . Note that this is a justification for the subplan with root  $N_G$ .
- Interpretation: If a subset of the NF of a target goal matches the gen-essence of a source node N, then the substitution provided by the match is used for the term generalization in the target, and the subproof for the goal at N can be replayed. If a subset of the NF of a target goal (node) matches the gen-lemma of a source node only, then the substitution provided by the match is taken for a generalization, and then the lemma application can be replayed.

## **3** Example: Proofs of Invariants

The following example stems from a case study at DFKI performed with VSE, a verification support environment [3]. The goal of this case study is to model a communication filter: From an input queue a message is checked for certain properties. If these properties hold, the message is sent to an output queue. In case the properties do not hold, it is sent to an error queue.

A message is a compound object of several components: the addressee, the sender, the subject, and the message text. The input queue (in), the output queue (out), as well as the error queue (err) are first-in-first-out queues with the following functions:

- $nil :\rightarrow queue$  generating the empty queue,
- *insert* : *message*  $\times$  *queue*  $\rightarrow$  *queue* inserts a message into a queue,
- $\in$ : message  $\times$  queue  $\rightarrow$  bool determining whether a message is contained in a queue,
- next :  $queue \rightarrow message$  returning the message from the queue which is handled next, and
- *rest* : *queue* → *queue* deletes the message that is handled next from the queue and leaving all other entries unchanged.

In addition, for the communication system there is a data base (base) of all clients.

The check whether a message can pass the filter is done in two steps: First, it is checked whether the sender is a legal client. A function  $known: name \times data\_base \rightarrow bool$  returns true if for the name there is an entry in the data base. Secondly, the message is evaluated, and a natural number is computed,  $value: message \rightarrow nat$ . Moreover, for each client in the data base there is a maximal value,  $max\_value: name \times data\_base \rightarrow nat$ . If the value of a message does not exceed the maximal value associated with the sender, then the respective message is allowed to pass. As values one could imagine, for instance, the allowed lengths of a message text.

For this scenario a state-based specification [10, 3] was used: We have several state variables for the different queues and for the client data base. Furthermore, some state transitions were specified for the insertion operation on queues, and for the check whether a message can pass the filter. Each state transition is specified by the details of the changes they produce, i.e., by defining the precondition and the postcondition of a state transition. In these pre- and postconditions a state variable prior to the execution of the state transition is quoted as opposed to the state variable after the transition has been performed. For example, in' denotes the input queue before the transition has been performed, and in is the input queue afterwards.

A state-based specification is called *correct*, if a first-order formula – the *invariant* – holds for all reachable states. Hence, this invariant has to be proved for the initial state, and for all states that can be reached from the initial state. The invariant from our case study is:

$$\begin{array}{ccc} x \in out & \rightarrow & \begin{pmatrix} known(sender(x), base) \land \\ value(x) \leq max\_value(sender(x), base) \\ \neg known(sender(x), base) \lor \\ value(x) > max\_value(sender(x), base) \end{pmatrix} \land$$

During the verification process the original large proof obligation has been decomposed into seven smaller proof obligations denoted by proofinv-*i* for i = 1, ..., 7. By simplifications and equation applications each proofinv-*i* is decomposed into several simpler proof obligations. For instance, proofinv-5, proofinv-6, proofinv-7 are each reduced to eight subgoals. We shall have a look at the proofs of these subgoals. In the following examples the shaded parts of proof obligations indicate the *relevant* parts of the proof obligations. Note, how these relevant parts occur in several proof obligations giving rise to a reuse of proofs.

proofinv-5 is a rather large proof obligation:

 $\begin{array}{l} in' \not\equiv nil, x \in out' \rightarrow known(sender(x), base') \land \\ value(x) \leq max\_value(sender(x), base'), \\ x \in err' \rightarrow \neg known(sender(x), base') \\ \lor value(x) > max\_value(sender(x), base'), \neg known(sender(next(in')), base), \\ err \equiv insert(next(in'), err') \land out \equiv out' \land in \equiv rest(in') \vdash \\ (x \in out \rightarrow known(sender(x), base') \land \\ value(x) \leq max\_value(sender(x), base')) \land (x \in err \rightarrow \\ \neg known(sender(x), base') \lor value(x) > max\_value(sender(x), base')). \end{array}$ 

All but the resulting third and eighth subgoal can easily be simplified and proved. Originally, for the 19 proof steps of proofinv-5 ten user interactions were needed. By internal analogy approximately 50% of the interactions can be saved.

- 5.3.  $known(sender(x), base'), x \in err, err \equiv insert(next(in'), err'),$   $out \equiv out', in \equiv rest(in') \vdash$   $value(x) > max\_value(sender(x), base'), x \in err', x \in out',$   $known(sender(next(in')), base'), in' \equiv nil$ is proved by
  - manually suggesting the lemma

$$x \in insert(Y, Z) \land x \notin Z \Rightarrow x \equiv Y.$$
<sup>(2)</sup>

With the substitution  $[Y \leftarrow next(in'), Z \leftarrow err']$  the application of this lemma gives

$$x \equiv next(in'). \tag{3}$$

• By simplification with (3) we obtain a subgoal  $\ldots, H, \ldots \vdash \ldots, H, \ldots$  where H abbreviates known(sender(x), base').

The justifications at the root node of 5.3. look as follows: essence made up from all the shaded formulae.

**lemma:**  $\{x \in err, err \equiv insert(next(in'), err'), \neg(x \in err')\}$  is constructed from  $x \in err$ ,  $err \equiv insert(next(in'), err')$  at the left hand side of the proof obligation and  $x \in err'$  at the right hand side. **lemma** provides the elements of the essence relevant for the lemma application. The other shaded formulae are relevant for the remaining proof steps. g-lemma:  $\{x \in B, B \equiv insert(Y, A), \neg(x \in A)\}$ .

5.8. known(sender(x), base'), x ∈ err, err ≡ insert(next(in'), err'), out ≡ out', in ≡ rest(in'), known(sender(x), base'), value(x) ≤ max\_value(sender(x), base') ⊢ value(x) > max\_value(sender(x), base'), x ∈ err', known(sender(next(in')), base'), in' ≡ nil can be proved by analogy to proof obligation 5.3. because the essence of 5.3. is a subset of the NF of 5.8. as well. **proofinv-6** is decomposed into eight proof obligations. All but the resulting third and eighth subgoal can be immediately simplified and proved automatically. The more complicated subproofs are outlined below. Originally, for the 22 proof steps of proofinv-6 13 user interactions were needed. By internal analogy approximately 80% of the interactions can be saved.

- 6.3.  $known(sender(x), base'), x \in err, out \equiv out', in \equiv rest(in')$   $max\_value(sender(next(in')), base') < value(next(in')),$   $known(sender(next(in'), base')), err \equiv insert(next(in'), err'), \vdash$   $value(x) > max\_value(sender(x), base'), x \in err', x \in out', in' \equiv nil.$ is proved by
  - reusing the lemma application from 5.3. because the lemma justification holds in 6.3. The rest of the subproof differs though.
  - Then interactively generalizing max\_value(sender(x), clients') to X and value(x) to Y at node N<sub>G</sub> results in the problem ..., X < Y, ... ⊢ ..., Y > X,.... This goal can be proved automatically.
  - This subproof automatically uses the lemma  $X < Y \leftrightarrow Y > X$ .

essence at the root node of 6.3. is provided by all the shaded formulae. gen-essence at  $N_G$  is  $\{X < Y, \neg(Y > X)\}$ .

6.8. known(sender(x), base'), x ∈ err, in ≡ rest(in'), known(sender(x), base'), max\_value(sender(next(in')), base') < value(next(in')), known(sender(next(in'), base')), err ≡ insert(next(in'), err'), out ≡ out', value(x) ≤ max\_value(sender(x), base') ⊢ value(x) > max\_value(sender(x), base'), x ∈ err', in' ≡ nil, is proved by reusing the proof of 6.3. because essence of 6.3. is a subset of 6.8.'s NF.

Only the third and eighth subgoal of **proofinv-7** can be simplified and proved immediately. The other goals are proved by analogy. Originally, for the 40 proof steps of proofinv-7 31 user interactions were needed. By internal analogy approximately 90% of the interactions can be saved.

- 7.1.  $x \in out$ , known(sender(next(in')), base'),  $err \equiv err'$ ,  $out \equiv insert(next(in'), out'), in \equiv rest(in') \vdash$   $known(sender(x), base'), x \in err', x \in out'$   $max\_value(sender(next(in')), base') < value(next(in'))in' \equiv nil$ Is proved by reusing the subproof of 5.3.
- 7.2.  $x \in out$ , known(sender(next(in')), base'),  $err \equiv err', out \equiv insert(next(in'), out'), in \equiv rest(in') \vdash$   $value(x) \leq max_value(sender(x), base'), x \in err', x \in out',$  $max_value(sender(next(in')), base') < value(next(in')))in' \equiv nil$

The lemma application of 7.1. is reused. Then at  $N_G$ , interactive generalization yields  $\ldots \vdash \ldots, X \leq Y, Y < X, \ldots$  which can be proved automatically. This provides the gen-essence  $\{\neg(X \leq Y), \neg(Y < X)\}$  for  $[X \leftarrow value(x), Y \leftarrow max\_value(sender(x), base')].$ 

7.4. For  $x \in out$ , known(sender(next(in')), base'),  $err \equiv err'$ ,  $out \equiv insert(next(in'), out')$ ,  $in \equiv rest(in') \vdash$  known(sender(x), base'), known(sender(x), base'),  $x \in out'$ ,  $max\_value(sender(next(in')), base') < value(next(in'))$ ,  $in' \equiv nil$ .

the subproof of 7.1 can be reused.

7.5. For  $x \in out$ , known(sender(next(in')), base'),  $err \equiv err'$ ,  $out \equiv insert(next(in'), out')$ ,  $in \equiv rest(in') \vdash$   $value(x) \leq max\_value(sender(x), base')$ , known(sender(x), base'),  $x \in out'$ , max\\_value(sender(next(in')), base') < value(next(in')), in' \equiv nil.

the subproof of 7.1 can be reused.

7.6. For  $x \in out, value(x) > max\_value(sender(x), base'),$   $known(sender(next(in')), base), err \equiv err'$   $out \equiv insert(next(in'), out'), in \equiv rest(in') \vdash$   $known(sender(x), base'), x \in out',$  $max\_value(sender(next(in')), base') < value(next(in'))in' \equiv nil.$ 

the subproof of 7.1 can be reused.

7.7.  $x \in out, value(x) > max value(sender(x), base'),$   $known(sender(next(in')), base'), err \equiv err',$   $out \equiv insert(next(in'), out'), in \equiv rest(in') \vdash$   $value(x) \leq max_value(sender(x), base'), x \in out',$  $max_value(sender(next(in')), base') < value(next(in')), in' \equiv nil.$ 

The lemma application of 7.1. can be reused. Then the resulting subgoal is proved by automatically applying the lemma  $X > Y \leftrightarrow \neg(X \leq Y)$ . The first step of 7.1. can be replayed because its lemma justification holds.

## 4 Conclusion and Future Work

Since user interaction accounts for the lions share of the costs in program verification, the paper has addressed the problem of saving user interaction in the verification of state-based specifications.

¿From the given examples it is clear that and how whole subproofs, generalizations, and lemma applications can be reused if the justifications hold for the target subproblem. In our example the savings of user interactions achieved by internal analogy sums up to about 80%.

Our technique is based on the general idea of internal analogy that transfers source subproofs to target subproofs in the same proof attempt. It turns out that state-based specifications give rise to many similar proof obligations in their verification. Therefore, we provide mechanisms to replay subproofs in this kind of formal verification. We identified common patterns of subproofs and their justifications in order to employ them for the reuse of subproofs and proof steps.

The presented techniques are just a beginning. More elaborate justifications and mapping techniques will be explored to obtain even more reuse. The retrieval and the replay have to be extended to handle multiple sources.

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